

Series

**S1**

... with single chamber

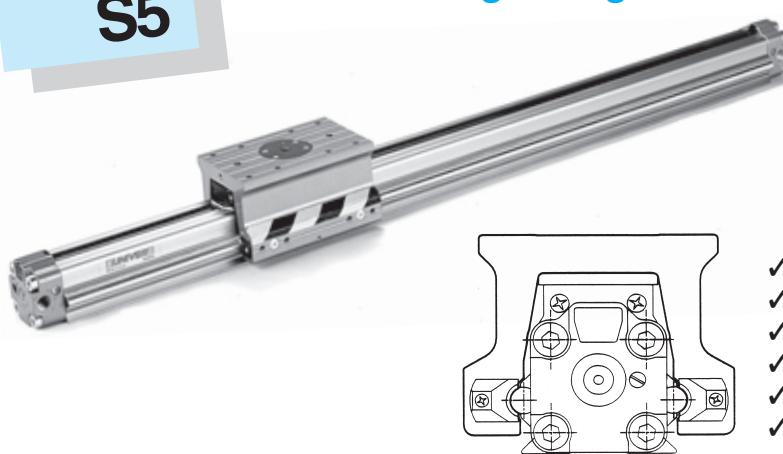


- ✓ Extruded profile in aluminium Ø 16 ÷ 50 mm.
- ✓ Stroke to 5 m.
- ✓ Various supply port configurations available.
- ✓ Various carriage types.
- ✓ High translation speed 1 ÷ 3 m/s.

Series

**S5**

... with integrated guides

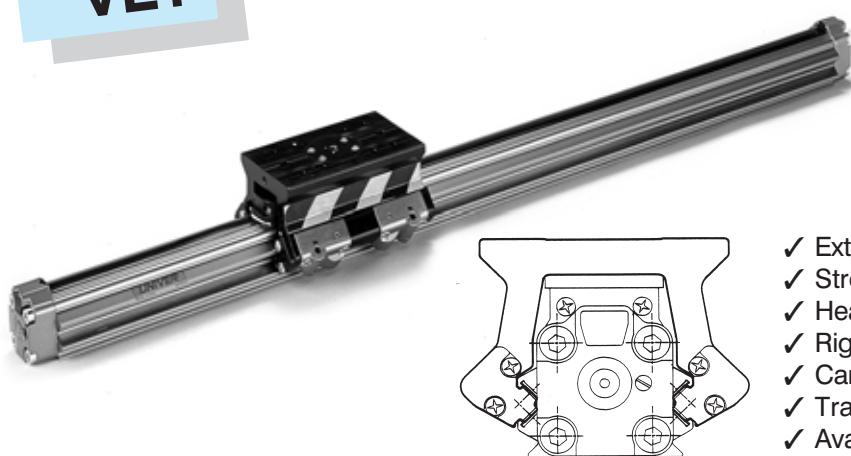


- ✓ Extruded profile in aluminium Ø 25 ÷ 50 mm.
- ✓ Stroke to 6 m.
- ✓ Flexible bearing system.
- ✓ Plastic bearings reduce noise.
- ✓ Translation speed 0,2 ÷ 1,5 m/s.
- ✓ Available with locking unit.

Series

**VL1**

... with integrated guides 90°



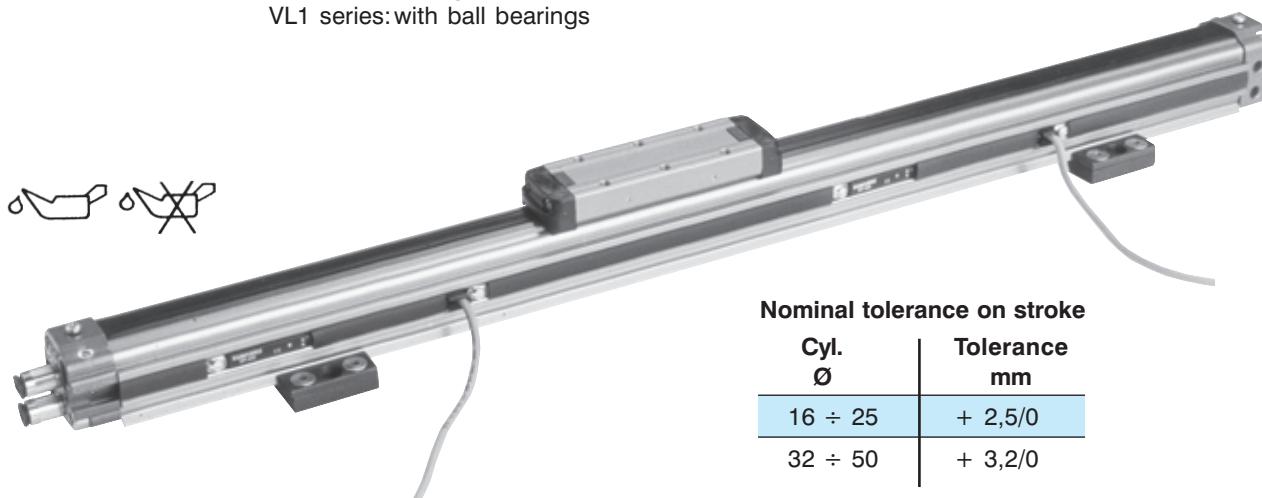
- ✓ Extruded profile in aluminium Ø 25 ÷ 50 mm.
- ✓ Stroke to 6 m.
- ✓ Heavy duty precision series.
- ✓ Rigid ball bearing system.
- ✓ Carriage slide on ball bearings.
- ✓ Translation speed 0,2 ÷ 2 m/s.
- ✓ Available with locking unit.

## TECHNICAL CHARACTERISTICS

Working pressure: 3-10 bar  
 Ambient temperature: -20°C ÷ +80°C  
 Fluid: filtered air, **with or without lubrication**  
 up to 500 mm  
 Bore size: Ø 16-25-32-40-50 mm  
 Standard strokes: up to 5 meters (Ø 16 mm)  
 up to 6 meters (Ø 25 ÷ 50 mm)  
 Min. speed required for regular translation: 7 ÷ 20 mm/s.  
 Translation speed: 3 m/s max.  
 Carriage types: standard, medium, long, double medium  
 Integrated guides: S5 series: round steel shafts  
 VL1 series: steel foils at 90°  
 External carriage slide: S5 series: with plastic  
 sliding shoes  
 VL1 series: with ball bearings

## Upon request

- Magnetic version for S1 series (except for Ø 16 magnetic version standard); for S5 series a special magnetic sensor holder extrusion DKS series is foreseen (section accessories page 6-V).
- Magnetic sensor DH-series - DF-series (Ø 16) (section accessories page 2-V).
- Slide units with standard or long carriage for S1 series (J30 - J31 series) page 47.
- Locking unit for S5 - VL1 series (L6 series) page 7.



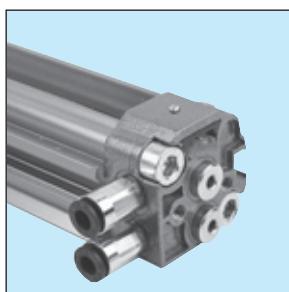
## Nominal tolerance on stroke

Cyl. Ø	Tolerance mm
16 ÷ 25	+ 2,5/0
32 ÷ 50	+ 3,2/0

**End-caps** in die-cast light alloy with various supply port options (see picture below).

The unique method of stripseal attachment permits easy assembly and disassembly, without needing tools or continuous adjustment.

## Ø 16 mm

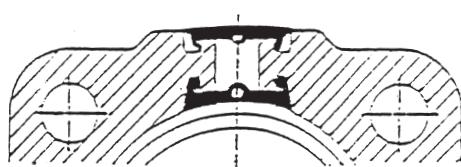


Double side supply

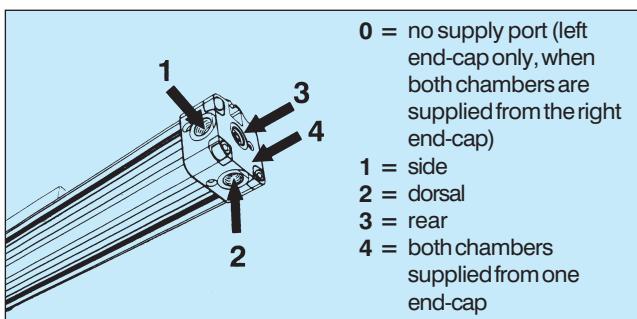


Double rear supply

**Slideway sealing.** The pneumatic sealing is achieved through an elastomer stripseal reinforced with Kevlar. This system guarantees dimensional stability even with high translation speeds. The external protection seal consists of a thermoplastic stripseal reinforced with Kevlar.



## Ø 25 ÷ 50 mm



**Piston - Carriage assembly** in extruded aluminium alloy with thermoplastic guide bearings. The piston is fitted with double lip seals which automatically self-compensate against wear; upon request it is possible to fit it with permanent magnets (S1 series).

**Cylinder barrel** in extruded aluminium alloy with internal and external anodisation.

**Pneumatic adjustable cushions** with two regulation screws in each end-cap allow an improved regulation of piston deceleration.

**Mechanical rubber shock absorbers** avoid mechanical stress and reduce machinery noise (below 50 dB).

### Examination and verification of the cushioning

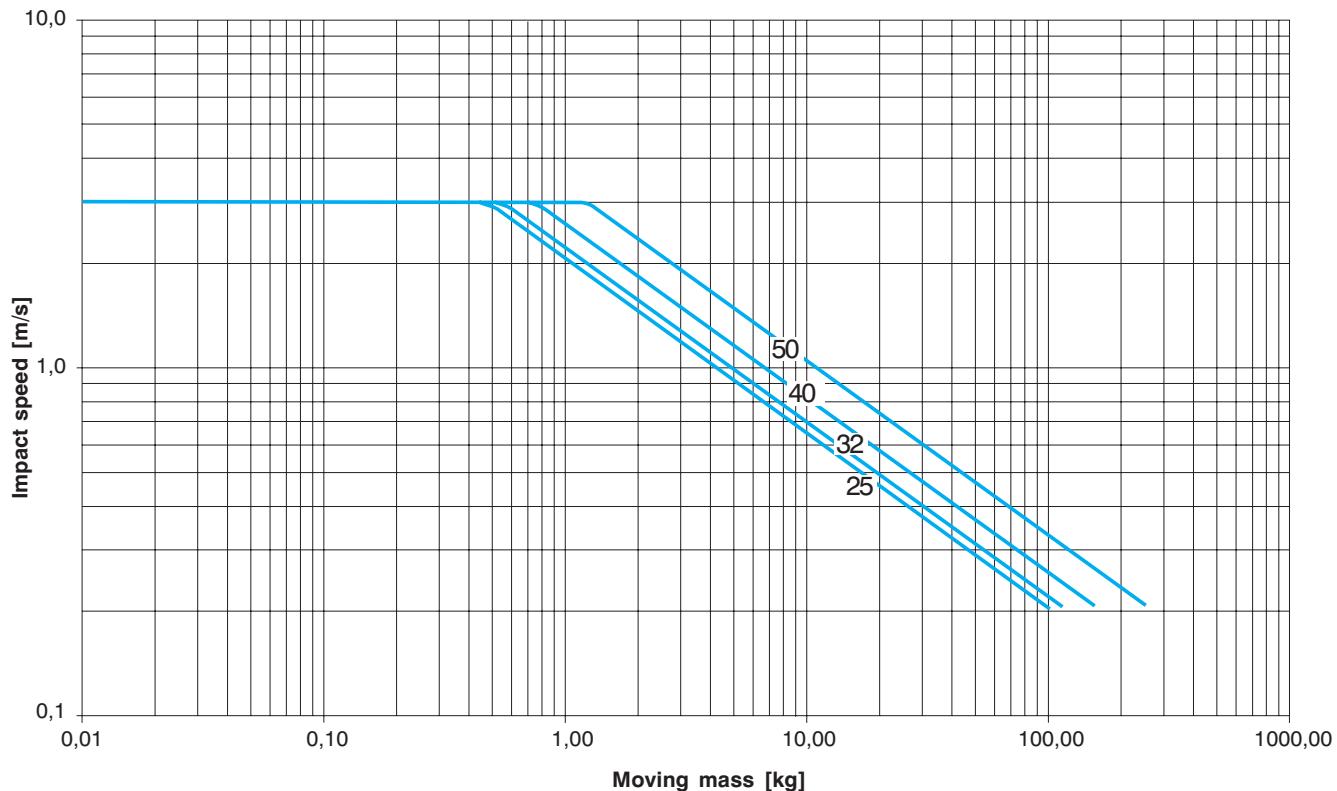
In a system with moving masses, as in the case of rodless cylinders, it is essential to control the dissipation of the system's kinetic energy as it is brought to a stop.

It is necessary, first of all, to establish and verify the most suitable method of cushioning the system, in order to avoid the moving mass (carriage with load) striking against the end-caps and compromising the life of the cylinder. If the point corresponding to a given load and speed lies **beneath** the appropriate curve, the cushioning is able to absorb the kinetic energy of the system.

Vice versa if the point lies **above** the curve, the cushioning **is not able to absorbe the kinetic energy**, in which case you must:

- a) decrease the load and maintain the translation speed
- b) decrease the speed and maintain the load
- c) select a cylinder with a bigger bore.

**The cushioning capacity is shown in the diagram below, referenced to the final speed as the carriage approaches the end-caps, for S1 - S5 - VL1 series.**



If it is not possible to absorb the kinetic energy with the cushioned end-caps and modify the parameters (a-b-c shown at page 11), an additional cushioning is necessary to reduce the load speed before the cylinder strikes the cushion.

The additional cushion can be:

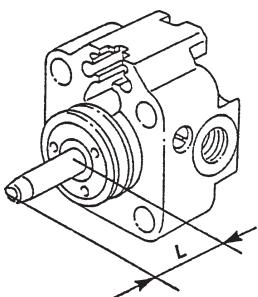
- a **pneumatic cushion** with electronic control;
- a **hydraulic cushion**, available on the market.

The mass movement generates loads to the cylinder, connected both to the weight forces (load values are constant) and to the inertia forces which originate in the acceleration or deceleration phases of the piston at the beginning and at the end of the stroke.

A typical fatigue stress arises in which the load value affects the life of the structure. The following acceptable loads refer to a life expectancy of 20000 km.

The indicated values (in the corresponding pages of each series) represent the maximum values of the forces and of the torques which can be developed in acceleration phases. Thus, in order to evaluate if an application is correct, the generated inertia forces and the corresponding torque should be calculated.

To calculate the inertia forces, the length L of the deceleration distance must be known. If the pneumatic cushion of the cylinder head is used, the values are:



$\varnothing$ (mm)	L (mm)
16	16,5
25	25,0
32	32,5
40	41,5
50	52,0

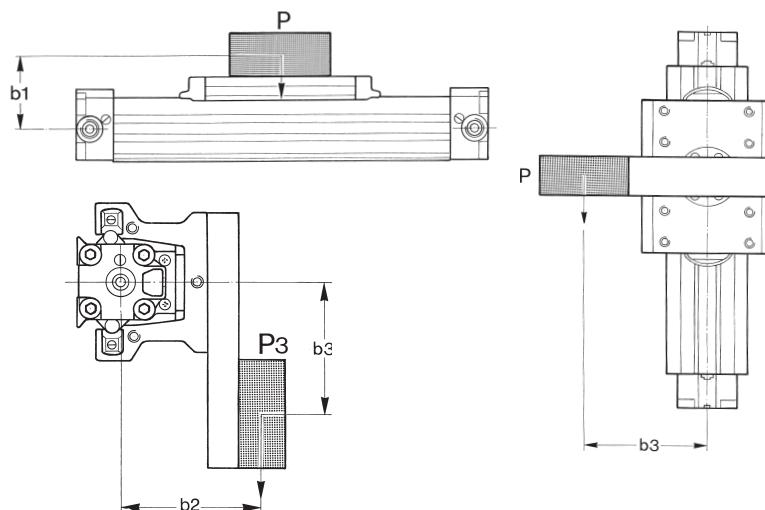
The usual formulas of mechanics are then applied. For instance, when moving a mass M (kg) at an impact speed V (m/s) with b<sub>1</sub>, b<sub>2</sub> and b<sub>3</sub> (mm) arms to the longitudinal axis of the piston, the inertia force F, in longitudinal direction and the corresponding torques are calculated as follows:

$$F(N) = M \cdot a = M \cdot \frac{V^2}{2 \cdot (L \cdot 10^{-3})}$$

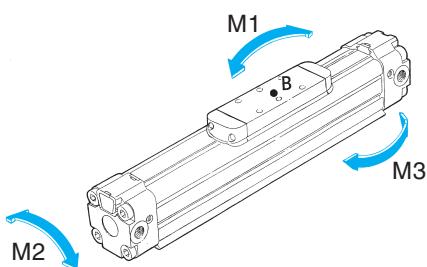
$$M_1 \cdot (Nm) = F \cdot (b_1 \cdot 10^{-3})$$

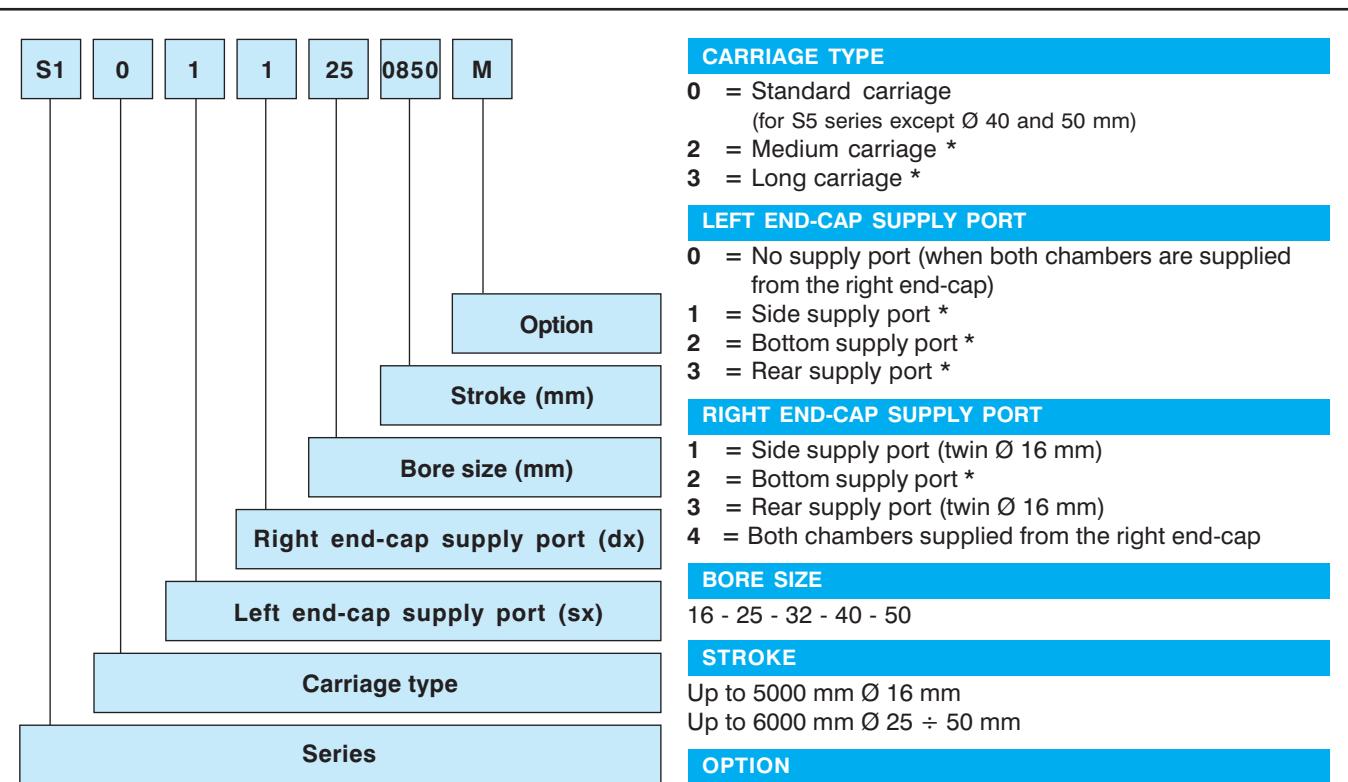
$$M_2 \cdot (Nm) = M \cdot g \cdot (b_2 \cdot 10^{-3})$$

$$M_3 \cdot (Nm) = F \cdot (b_3 \cdot 10^{-3})$$



While F, M<sub>1</sub> and M<sub>3</sub> can have both static and inertia components, M<sub>2</sub> is a static component only.



**SERIES**

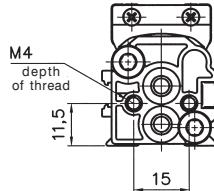
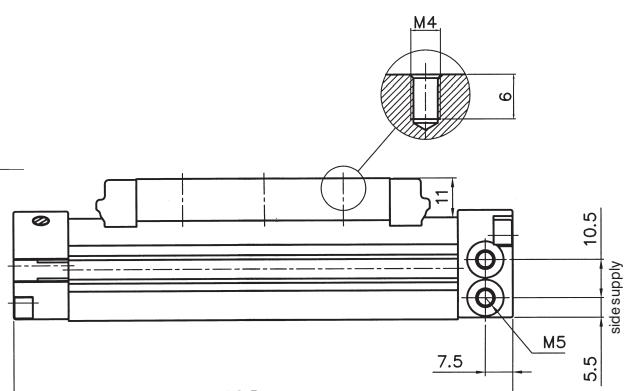
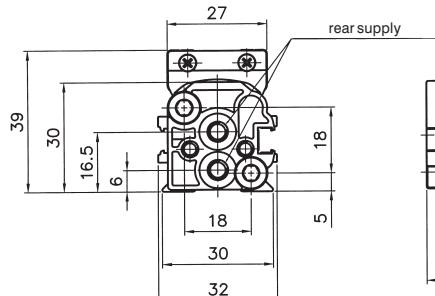
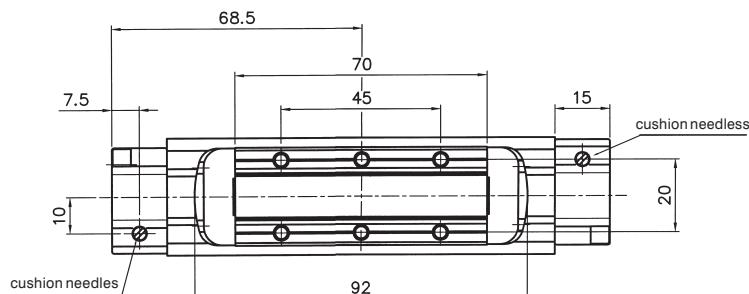
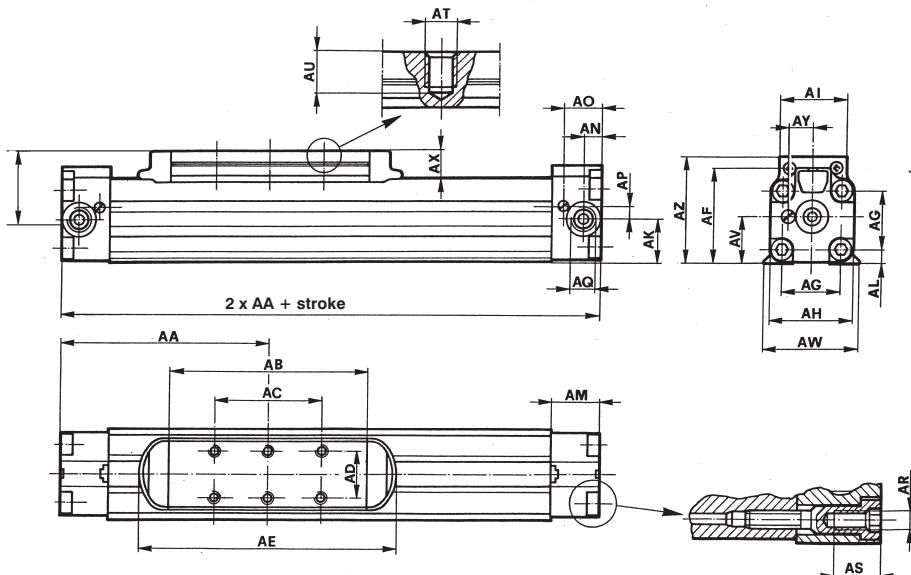
S1 = Single chamber

S5 = Integrated guides/plastic bearings

\* = Except Ø 16 mm



## Rodless cylinders with standard carriage - 6 fixing holes

**Ø 16 mm**Mass stroke "0"  
0,310 kg.Increase per 100 mm stroke  
0,104 kg.**Ø 25 ÷ 50 mm**

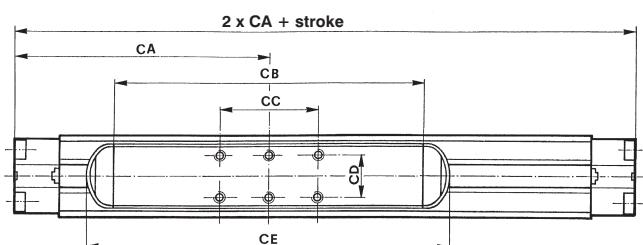
Cyl Ø	AA	AB	AC	AD	AE	AF	AG	AH	AI	AK	AL	AM	AN	AO	AP	AQ	AR	AS	AT
25	100	95	50	24	130	48,3	28	40,5	33	20,2	7	24	7,4	18,2	5,7	G1/8	M5	12	M5
32	125	118	65	31	156	57	35	50	40	25,3	8	29	10,3	22,5	7,3	G1/4	M6	15,5	M6
40	150	134	65	31	177	74	44	64	44	33,8	11,8	33	12,5	26,5	8,7	G3/8	M8	20	M6
50	175	164	105	39	211	90,7	55	80	54	41,4	14,7	33	14,2	25,7	11,8	G3/8	M10	20	M8
Cyl Ø	AU	AV	AW	AX	AY	AZ	Mass (kg) at "0" stroke										Weight increase (kg) per additional 100mm stroke		
25	9	22,8	42,8	16	12,2	57,6											0,750		
32	9	28	54,5	16	14,2	66,2											0,325		
40	11	37	67	19,5	16,5	85,8											2,600		
50	12	47,7	86	20,5	19,1	103											4,785		

Values of the static load; please note that under dynamic conditions the load must be reduced due to the effects associated with the speed. The torque is the product of load (Newton) per arm (meters), i.e. the distance between the center of gravity of the load and the longitudinal axis of the piston (technical characteristics see page 11-12-II).

Force (at 6 bar)				Load			Bending moment			Torque			Bending moment		
Cyl. Ø	F (N)	P1 (N)	P2 (N)	P3 (N)	M1 (Nm)	M2♦ (Nm)	M3 (Nm)	M1 (Nm)	M2♦ (Nm)	M3 (Nm)	M1 (Nm)	M2 (Nm)	M3 (Nm)		
16	125	100	100	25	5	0,2	0,8	-	-	-	-	-	-	-	
25	250	200	200	50	8	2	3	14	3	5	25	6	9		
32	420	250	250	65	9	3	4	15	4	7	28	8	12		
40	640	350	350	90	11	9	14	16	14	20	31	27	39		
50	1050	500	500	125	19	13	19	29	20	30	52	36	53		

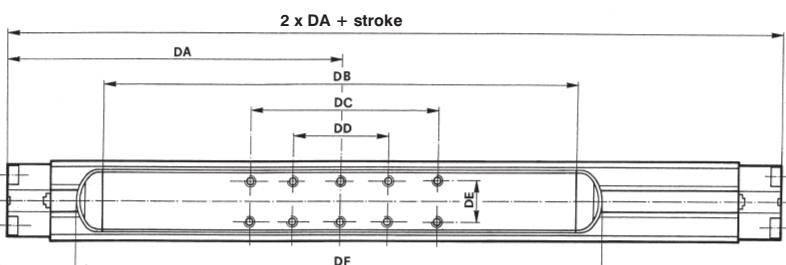
♦ It is not advisable to use the cylinder in applications with high stress.

### Medium carriage - 6 fixing holes for cylinders Ø 25 ÷ 50 mm



Cyl. Ø	CA	CB	CC	CD	CE	Mass (kg) at "0" stroke
25	114,5	125	50	24	160	0,84
32	142,5	153	65	31	191	1,48
40	169	172	65	31	215	2,91
50	205	224	105	39	271	5,55

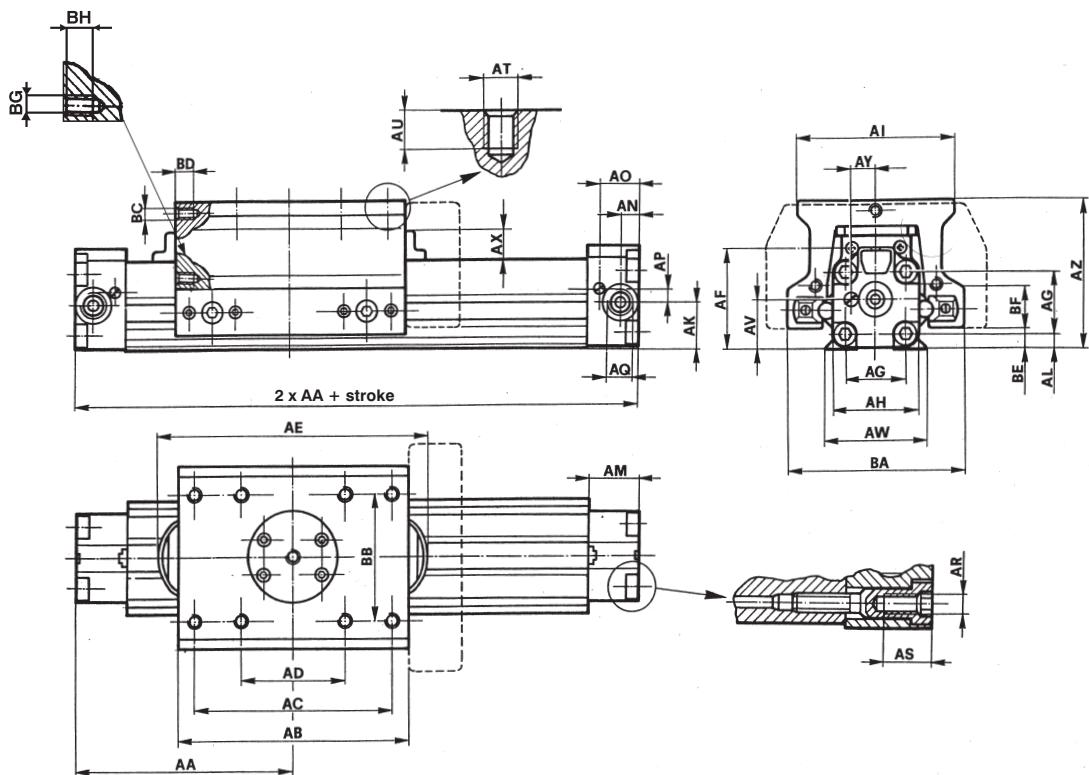
### Long carriage - 10 fixing holes for cylinders Ø 25 ÷ 50 mm



Cyl. Ø	DA	DB	DC	DD	DE	DF	Mass (kg) at "0" stroke
25	147,5	190	100	50	24	225	1,05
32	190	248	130	65	31	286	1,93
40	225	284	130	65	31	327	3,80
50	277	364	315	105	39	411	7,33

N.B. in cases where the rodless cylinder is mounted on external rigid guides, it is necessary to fit the oscillating mounting bracket onto the carriage (SF- 24 . . . series, see page 23-II), in order to isolate the cylinder from the rigid structure.  
Other accessories from page 22-II.

## Rodless cylinders with integrated guides and standard carriage - 8 fixing holes

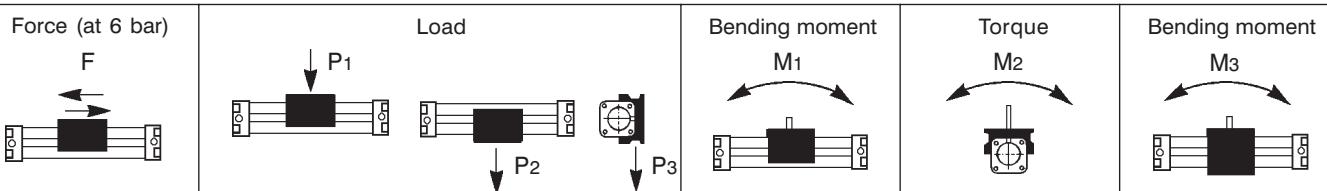


Cyl. Ø	AA	AB	AC	AD	AE	AF	AG	AH	AI	AK	AL	AM	AN	AO	AP	AQ	AR	AS	AT
25	100	106	90	50	130	48,3	28	40,5	70	20,2	7	24	7,4	18,2	5,7	G 1/8	M5	12	M6
32	125	140	115	55	156	57,0	35	50	88	25,3	8	29	10,3	22,5	7,3	G 1/4	M6	15,5	M8
40							44	64	90	33,8	11,8	33	12,5	26,5	8,7	G 3/8	M8	20	M8
50							55	80	100	41,4	14,7	33	14,2	25,7	11,8	G 3/8	M10	20	M8

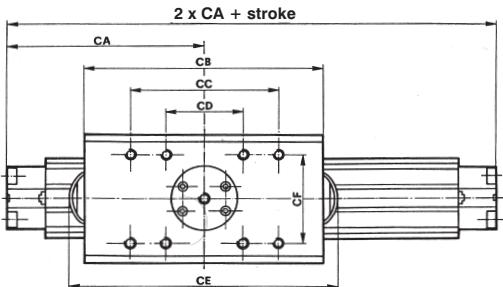
Cyl. Ø	AU	AV	AW	AX	AY	AZ	BA	BB	BC	BD	BE	BF	BG	BH	Mass	Weight increase (kg)
															(kg) at "0" stroke	per additional 100 mm stroke
25	10	22,8	42,8	16	12,2	71,8	85	50	M6	15	5,7	24	M6	15	1,625	0,365
32	12	28	57	16	14,2	82,5	100	67,5	M6	15	7	24,5	M6	15	2,775	0,495
40	14	37	67	19,5	16,5	106,6	135	65	M6	15	7	39	M6	15		0,92
50	16	47,7	86	20,5	19,1	123,7	149	76,5	M8	16	7,2	41	M6	15		1,28

The dotted line indicates the overall dimensions of the locking unit; fixing holes of the locking unit see page 8-II.

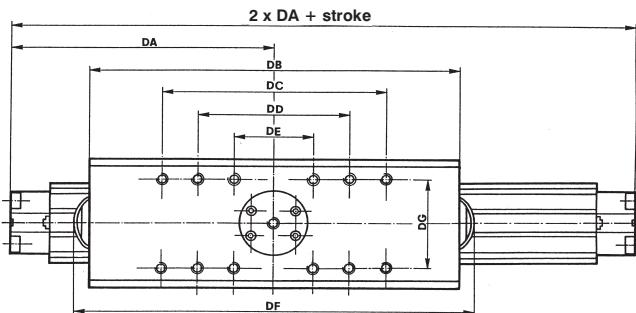
Values of the static load; please note that under dynamic conditions the load must be reduced due to the effects associated with the speed. The torque is the product of load (Newton) per arm (meters), i.e. the distance between the center of gravity of the load and the longitudinal axis of the piston.



Cyl. Ø	Standard carriage			Medium carriage			Long carriage			
	F (N)	P1 (N)	P2 (N)	P3 (N)	M1 (Nm)	M2 (Nm)	M3 (Nm)	M1 (Nm)	M2 (Nm)	M3 (Nm)
25	250		400		13	8	16	20	10	25
32	420		400		20	9	27	30	12	40
40	640		600		not foreseen			60	30	80
50	1050		800		not foreseen			85	50	110
								150	75	210

**Medium carriage - 8 fixing holes**


Cyl. Ø	CA	CB	CC	CD	CE	CF	Mass (kg) at "0" stroke
25	114,5	136	90	50	160	50	1,93
32	142,5	175	115	55	191	67,5	3,265
40	169	205	180	75	215	65	6,095
50	205	258	190	80	271	76,5	10,03

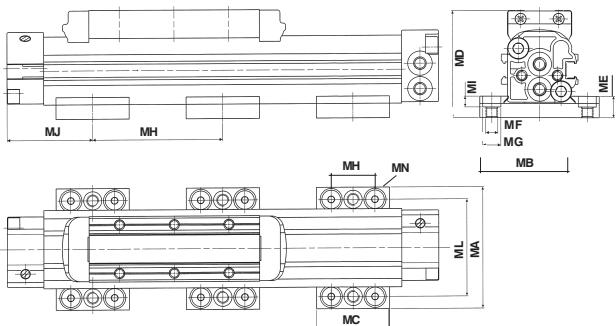
**Long carriage - 12 fixing holes**


Cyl. Ø	DA	DB	DC	DD	DE	DF	DG	Mass (kg) at "0" stroke
25	147,5	201	130	90	50	225	50	2,64
32	190	270	175	115	55	286	67,5	4,65
40	225	317	280	185	75	327	65	8,60
50	277	398	320	200	80	411	76,5	14,04

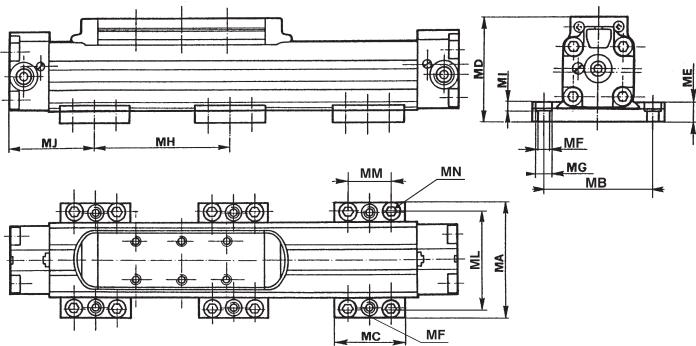
Accessories from page 22.

### Mounting plate for S1 series

**Ø 16 mm**



**Ø 25 ÷ 50 mm**

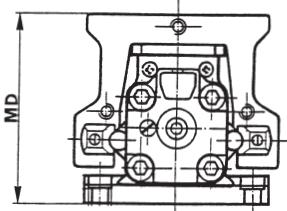


Cyl. Ø	MA	MB	MC	S1	S5	VL1	ME	MF	MG	MH	MI	MJ	ML*	MM	MN	Mass (kg)	Part number
16	50	40	30	44,8	-	-	9	M5	8	400 $\diamond$ 4,5	35	40	-	M6	0,083	SF - 12016	
25	78,5	63,5	50	65,6	79,8	82,3	12	M8	11	500 $\diamond$ 6,5	55	65,5	30	M6	0,310	SF - 12025	
32	92	77,5	50	74,2	90,5	90,5	12	M8	11	600 $\diamond$ 5,5	60	79,5	30	M6	0,340	SF - 12032	
40	117	96	60	95,8	116,6	116	15	M10	14	700 $\diamond$ 8	70	96	37,5	M8	0,660	SF - 12040	
50	136	115	60	113	133,7	136,2	15	M10	14	800 $\diamond$ 8	70	115	37,5	M8	0,700	SF - 12050	

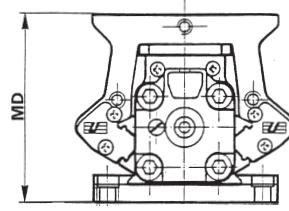
◆ Max. dimensions in order to limit the deflection of the cylinder according to the stroke and in order to ensure a correct fixing.

\* For Ø 16-40-50 mm, MB and ML have the same value.

### Mounting plate for S5 Series



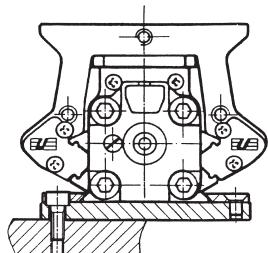
### Mounting plate for VL1 Series



#### How to mount plates:

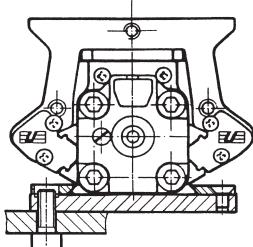
Plates are mounted by means of standard screws without disassembling any part of the cylinder (for all series).

#### Upper mounting

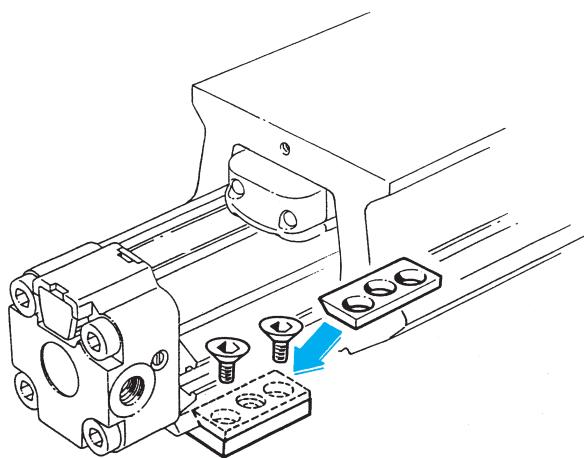


Cyl. Ø	
25 - 32	M6
40 - 50	M8

#### Lower mounting

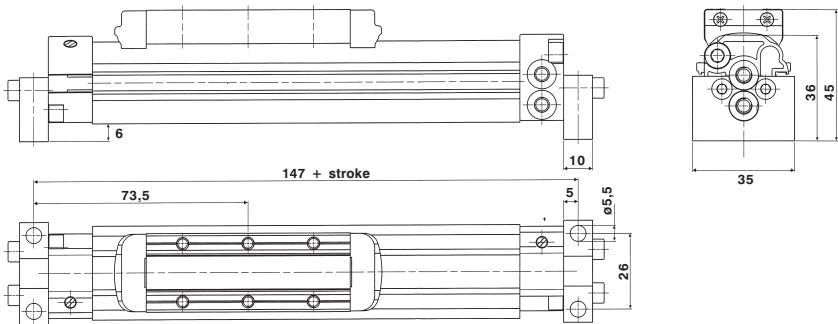


Cyl. Ø	
25 - 32	M8
40 - 50	M10

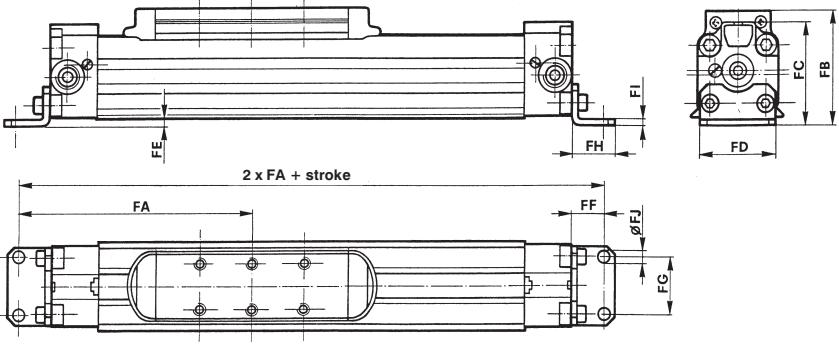


**Mounting bracket for Ø 16 mm rodless cylinder  
Partnum. SF-13016**

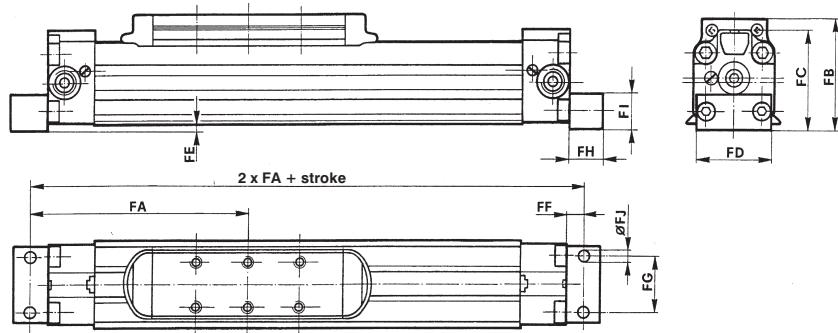
Mass kg 0,015



**Mounting bracket for  
Ø 25 - 32 mm rodless cylinder**



**Mounting bracket for  
Ø 40 - 50 mm rodless cylinder**



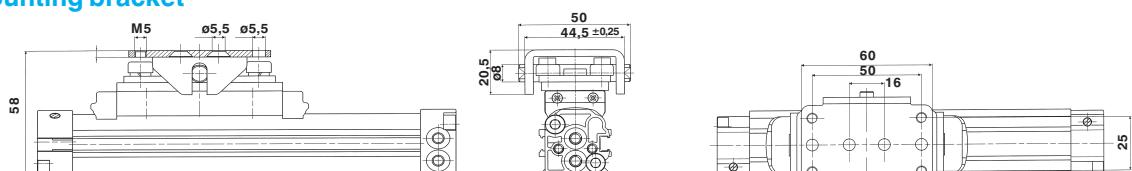
Cyl. Ø	FA	FB	FC	FD	FE	FF	FG	FH	FI	FJ	Mass (kg)	Part number
25	116	58,1	48,8	40	0,5	16	27	22	2,5	5,5	0,034	SF - 13025
32	143,5	68,7	59,2	48	2,5	18,5	36	26	3	6,5	0,053	SF - 13032
40	162,5	86,5	74,9	63	0,7	12,5	30	25	25	9	0,116	SF - 13040
50	189,5	104,3	92,4	79	1,3	12,5	40	25	30	9,3	0,170	SF - 13050

Mounting brackets are ONLY recommended for short strokes i.e. less than 400 mm

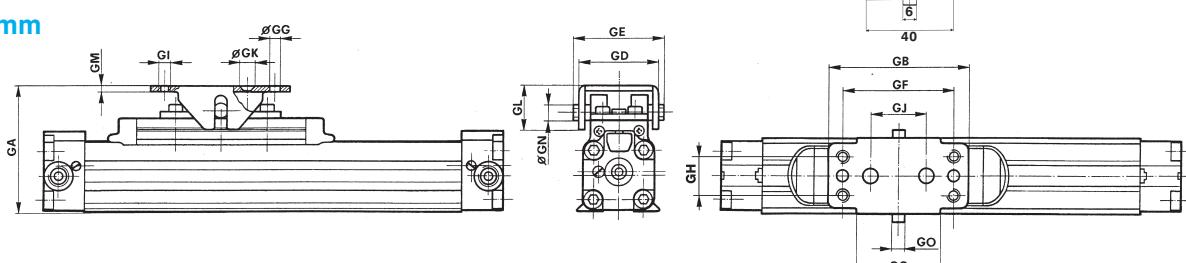
**Oscillating mounting bracket**

**Ø 16 mm  
Part num.  
SF-24016**

Mass  
Kg 0,195

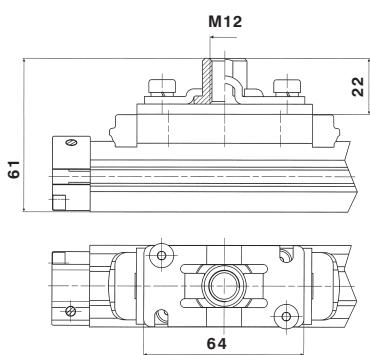
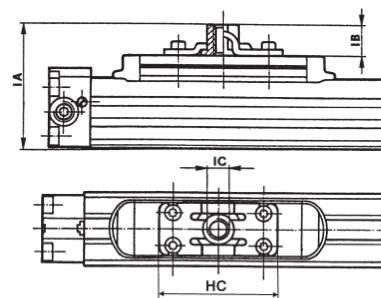


**Ø 25 ÷ 50 mm**



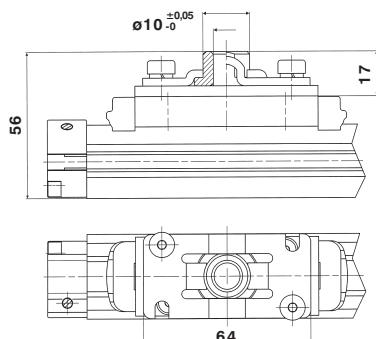
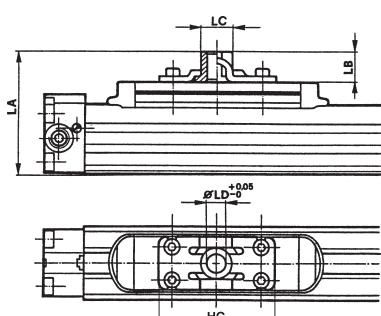
Cyl. Ø	GA	GB	GC	GD	GE	GF	GG	GH	GI	GJ	GK	GL	GM	GN	GO	Mass (kg)	Part number
25	73,5/±2,5	60	40	44,5/±2,5	50	50	5,5	25	M5	16	5,5	20,5	3	8	6,15	0,142	SF - 24025
32	89/±4	100	60	56/±4	64	80	5,5	30	M6	40	6,5	30	4	12	8,2	0,362	SF - 24032
40	108,5/±4	100	60	56/±4	64	80	5,5	30	M6	40	6,5	30	4	12	8,2	0,362	SF - 24032
50	not forseen																

**Female threaded connection**
**Ø 16 mm**

 Mass  
Kg 0,132

**Ø 25 ÷ 50 mm**


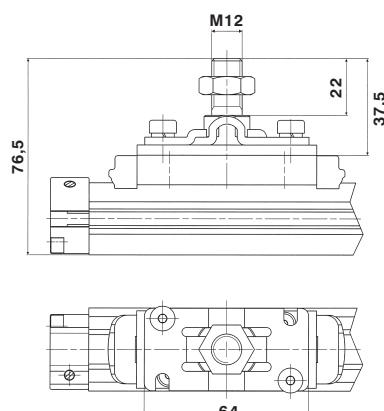
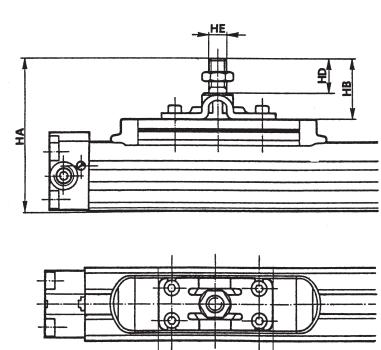
Cyl. Ø	IA	IB	IC	HC	Mass (kg)	Part number
25	75,6	18	M12	64	0,076	SF-26025
32	87,2	21	M14	84	0,157	SF-26032
40	106,8	21	M14	84	0,157	SF-26032
50	not foreseen					

**Female connection without thread**
**Ø 16 mm**

 Mass  
Kg 0,129

**Ø 25 ÷ 50 mm**


Cyl. Ø	LA	LB	LC	LD	HC	Mass (kg)	Part number
25	70,6	13	18	10	64	0,073	SF-28025
32	83,4	17,2	22	12	84	0,152	SF-28032
40	103	17,2	22	12	84	0,152	SF-28032
50	not foreseen						

**Male threaded pin**
**Ø 16 mm**

 Mass  
Kg 0,160

**Ø 25 ÷ 50 mm**


Cyl. Ø	HA	HB	HC	HD	HE	Mass (kg)	Part number
25	91,1	33,5	64	22	M12	0,105	SF-27025
32	107,7	41,5	84	24,3	M14	0,26	SF-27032
40	127,3	41,5	84	24,3	M14	0,26	SF-27032
50	not foreseen						